

IOTCLOUD'21 SYMPOSIUM - FINAL RESULTS

PAPERID TITLE AUTHORS	Review Marks (Total=100) (2 reviewers)	Presentation Marks (Total=40) (Total) (2 session chairs)	Opinion (Total = 10) (One faculty from the Univ. of Plymouth, UK)	Total (150)	Final
PID104 Title: Design and Implementation of Custom Built Quarantine Service Mobile Robot Using Deep Learning and ROS.	80.25	32	6	118.25	PRIZE - I
PID119 Title: 3DP-FAS: An Intelligent Quality Assurance System for 3D Printer.	80	29	8	117	PRIZE - II
PID122 Title: A novel temporal-spatial interpolation method for spatio-temporal air quality forecasting.	79.04	31	5	115.04	PRIZE-III